

ENTROPY-BASED BENCHMARKING METHODS

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WHAT IS BENCHMARKING?

- Series of **high-frequency** data: quarterly, monthly, daily
 - Timely data, only information about the short-term movements, less reliable



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- Benchmarking problem: combine the relative strengths of the **inconsistent** low- and high-frequency series



FIGURE: Benchmarking problem example (Source: Bloem et al. (2001), QNA Manual, IMF, Washington DC, p. 91)

Date	Indicator		Annual Data 2000A	Annual BI Ratio 2000A
	The Indicator	Period-to-Period rate of Change		
q1 1998	98.2			
q2 1998	100.3	2.6%		
q3 1998	102.2	1.4%		
q4 1998	100.8	-1.4%		
Sum	402.0		4,000.0	9.950
q1 1999	99.0	-1.8%		
q2 1999	101.6	2.6%		
q3 1999	102.7	1.1%		
q4 1999	101.5	-1.2%		
Sum	404.8	0.7%	4,161.4	10.280
q1 2000	100.5	-1.0%		
q2 2000	103.0	2.5%		
q3 2000	103.5	0.5%		
q4 2000	101.5	-1.9%		
Sum	408.5	0.9%	4,100.0	10.037



METHODS

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- Mathematical methods: deterministic, binding annual constraints
 - Denton (1971), Causey and Trager (1981)
- Statistical methods: stochastic, binding/nonbinding constraints
 - Regression methods: Chow and Lin (1971), ARIMA and generalized regression-based methods (Dagum and Cholette, 2006)



ASSESSMENT AND APPLICATIONS

- Chen (2007): 60 series from the US national economic accounts
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“the modified Denton proportional first difference method outperforms the other methods, though the Causey-Trager growth preservation model is a close competitor in certain cases.”
- Denton procedures: BEA, Statistics Netherlands
- Causey-Trager procedure: US Census Bureau (Brown 2010, Titova et al. 2010)



THIS PAPER

- Principle of movement *and* sign preservation
 - Motivation: abundant series are volatile and/or include both positive and negative values



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- Extended pro-rata distribution (semiGRAS method)
- Entropy-based benchmarking methods



NOTATIONS

$t = 1, \dots, T$ years

$i = 1, \dots, l$ sub-periods for each year

$\mathbf{z}_t = l \times 1$ vector of observed indicator series for year t

$\mathbf{x}_t = l \times 1$ vector of estimated benchmarked series for year t

$\mathbf{z} = (\mathbf{z}'_1, \mathbf{z}'_2, \dots, \mathbf{z}'_T)'$

$\mathbf{x} = (\mathbf{x}'_1, \mathbf{x}'_2, \dots, \mathbf{x}'_T)'$

$\mathbf{y} = T \times 1$ vector of annual data



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$\mathbf{y} = T \times 1$ vector of annual data

Consider annual constraints $\mathbf{v}'\mathbf{x}_t = y_t$ for all t , or

$$\begin{bmatrix} \mathbf{v}' & \mathbf{0}' & \vdots & \mathbf{0}' \\ \mathbf{0}' & \mathbf{v}' & \vdots & \mathbf{0}' \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{0}' & \mathbf{0}' & \dots & \mathbf{v}' \end{bmatrix} \mathbf{x} = \mathbf{B}\mathbf{x} = \mathbf{y}$$



DENTON (1971)

- The *additive first difference* (AFD) and *proportional first difference* (PFD) variants are:

$$f_{AFD} = (x_1 - z_1)^2 + \sum_{j=2}^N [(x_j - z_j) - (x_{j-1} - z_{j-1})]^2, \quad (1)$$

$$f_{PFD} = \left(\frac{x_1}{z_1} - 1\right)^2 + \sum_{j=2}^N \left(\frac{x_j}{z_j} - \frac{x_{j-1}}{z_{j-1}}\right)^2, \quad (2)$$

subject to $\mathbf{Bx} = \mathbf{y}$.



CAUSEY AND TRAGER (1981)

- Growth rate preservation principle:

$$f_{CT} = \sum_{j=2}^N \left(\frac{x_j}{x_{j-1}} - \frac{z_j}{z_{j-1}} \right)^2. \quad (3)$$

subject to $\mathbf{Bx} = \mathbf{y}$.



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- For all methods, changing sign is possible!



Apply the Generalized RAS idea to benchmarking (Günlük-Şenesen and Bates 1988, Junius and Oosterhaven 2003)

RESULT

The solution of the benchmarking problem is $\mathbf{X} = \mathbf{P}\hat{\mathbf{s}} - \mathbf{N}\hat{\mathbf{s}}^{-1}$, where the annual adjustment factors \mathbf{s} are derived from

$$\mathbf{s} = 0.5 \times \widehat{\mathbf{P}'\mathbf{z}}^{-1} \left(\mathbf{y} + \sqrt{\mathbf{y} \circ \mathbf{y} + 4 \times (\mathbf{P}'\mathbf{z}) \circ (\mathbf{N}'\mathbf{z})} \right),$$

where $\mathbf{Z} = (\mathbf{z}_1, \mathbf{z}_2, \dots, \mathbf{z}_T)$, $\mathbf{X} = (\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_T)$ and $\mathbf{Z} = \mathbf{P} - \mathbf{N}$.

Level preservation principle \Rightarrow **step problem** due to discontinuities between years



PROPORTIONAL FIRST DIFFERENCE PRESERVATION

- $\frac{x_j}{z_j} = \frac{x_{j-1}}{z_{j-1}} + \varepsilon_j$, denote $g_j = \frac{z_j}{z_{j-1}}$ and $\varepsilon_j = z_{j-1}\varepsilon_j$, then



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$$\bullet \left[\begin{array}{c} x_N - g_N x_{N-1} = \varepsilon_N \\ x_{N-1} - g_{N-1} x_{N-2} = \varepsilon_{N-1} \\ \vdots \\ x_2 - g_2 x_1 = \varepsilon_2 \end{array} \right] \Leftrightarrow \left[\begin{array}{ccccc} 1 & -g_N & 0 & \cdots & 0 \\ 0 & 1 & -g_{N-1} & & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ 0 & 0 & \cdots & 1 & -g_2 \end{array} \right] \begin{bmatrix} x_N \\ x_{N-1} \\ \vdots \\ x_1 \end{bmatrix} = \begin{bmatrix} \varepsilon_N \\ \varepsilon_{N-1} \\ \vdots \\ \varepsilon_1 \end{bmatrix}$$



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- RFD constraints: $C_P \tilde{x} = \varepsilon$



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- OLS?
- Generalized cross-entropy (Golan et al. 1996): principle of minimum discrimination information (Kullback 1959)
- Treat \tilde{x}_j as a discrete random variable with a compact support and M possible outcomes $\mathbf{r}_j = (r_{j1}, \dots, r_{jM})'$ with $2 \leq M < \infty$, i.e.,

$$\tilde{x}_j = \sum_{m=1}^M r_{jm} p_{jm} = \mathbf{r}'_j \mathbf{p}_j.$$



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- The GCE estimator is

$$\min_{\mathbf{p}, \mathbf{w}} l(\mathbf{p}, \mathbf{q}, \mathbf{w}, \mathbf{u}) = \mathbf{p}' \log(\mathbf{p}/\mathbf{q}) + \mathbf{w}' \log(\mathbf{w}/\mathbf{u}) \quad (4)$$

subject to

$$\tilde{\mathbf{y}} = \mathbf{\Gamma} \mathbf{Z} \tilde{\mathbf{x}} + \mathbf{V} \mathbf{w}, \quad (5)$$

$$\mathbf{z} = (\mathbf{I} \otimes \mathbf{z}') \mathbf{p}, \quad (6)$$

$$\mathbf{z} = (\mathbf{I} \otimes \mathbf{z}') \mathbf{w}, \quad (7)$$



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GROWTH RATE PRESERVATION

- $\frac{x_j}{x_{j-1}} = \frac{z_j}{z_{j-1}} + \zeta_j$, denote $g_j = \frac{z_j}{z_{j-1}}$ then



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- Work in progress



AGGREGATE INDICATORS OF CLOSENESS

- 1 Average absolute level difference: $AALD = \frac{\sum_{j=1}^N |x_j - z_j|}{N}$



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② Average absolute change difference:

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4 Average absolute relative proportional difference:

$$AARPD = \frac{100}{N-1} \sum_{j=2}^N \left| \left(\frac{x_j}{x_{j-1}} - \frac{z_j}{z_{j-1}} \right) / \frac{z_j}{z_{j-1}} \right|.$$



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$$\mathbf{r}'_j = (0.1, 0.55, 1, 1.45, 1.9) \times z_j \text{ with } \mathbf{q}'_j = (0.05 \ 0.05 \ 0.98 \ 0.05 \ 0.05)$$



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$$\mathbf{v}'_k = (-1.7, -0.85, 0, 0.85, 1.7) \times \sigma_z \text{ with}$$

$$\mathbf{u}'_k = (0.05 \ 0.05 \ 0.98 \ 0.05 \ 0.05) \text{ except for the annual constraints with}$$

$$\mathbf{u}'_k = (0 \ 0 \ 1 \ 0 \ 0)$$



RESULTS

TABLE: Some aggregate indicators

	f_{CT}	AALD	AACD	AAPD (%)	AARPD (%)
SemiGRAS	0.069	15.000	9.868	2.719	5.439
AFD Denton	1.198	18.324	5.972	17.510	13.260
AFD Entropy	0.323	16.774	6.270	10.360	9.440
PFD Denton	0.144	17.563	10.565	6.971	6.088
PFD Entropy	0.078	15.557	10.277	4.508	5.962
CT	0.044	16.553	10.348	3.761	5.761



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- 1 Advantages of entropy-based benchmarking methods
 - (Any choice of) Binding and/or nonbinding constraints
 - Reliability indicators for each element
 - Applicable for any size of yearly observations
 - Using non-sample information
 - Controlling for sign change
- 2 Plausible competitors to current benchmarking methods



THANKS FOR YOUR ATTENTION!

